

The Logic and Realism of the Hypothesis of Exploitation Ecosystems

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ABSTRACT: Hypotheses on trophic dynamics in terrestrial ecosystems fall into two major categories: those in which plants are assumed to be invulnerable to their consumers and those in which the build-up of plant biomass is assumed to require top-down control of folivores. The hypothesis of exploitation ecosystems (EEH) belongs to the latter category and focuses particularly on the consequences of the high energetic costs of maintenance of endotherms. Carnivorous endotherms require relatively high prey densities in order to break even. Moreover, they are dependent on folivorous prey during the limiting season, at least at high latitudes. The endotherm branch of the grazing web is thus predicted to collapse from three-link trophic dynamics (carnivores → folivores → plants → inorganic resources) to two-link dynamics (folivores → plants → inorganic resources) along gradients of decreasing primary productivity. Consequently, the vegetation of cold and unproductive areas is predicted to be under intense winter grazing pressure, which prevents the accumulation of aboveground plant biomass and excludes erect woody plants. In the most extreme habitats (e.g., polar deserts and their high alpine counterparts), even folivorous endotherms are predicted to be absent, and the scanty vegetation is predicted to be structured by preemptive competition. Within temperature-determined productivity gradients, EEH is corroborated by biomass patterns, by patterns in the structure and dynamics of carnivore, folivore, and plant communities, and by experimental results. The general idea of top-down trophic dynamics is supported for other autotroph-based systems, too, but the relevance and sufficiency of the energy constraint in explaining patterns in trophic dynamics appears to be variable. Moreover, critical empirical evidence for or against the capacity of folivorous insects to regulate plant biomass has not yet been obtained. Another open question is the ability of boreal and temperate browsers, evolved in productive environments with intense predation pressure and abundance of forage, to prevent the regeneration of the least palatable tree species. There are, thus, many open questions waiting to be answered and many exciting experiments waiting to be conducted.

In the current debate on trophic dynamics in terrestrial ecosystems, two main views can be distinguished. One emphasizes defenses themselves or the diversity of defensive strategies in herbivores and plants and maintains that strong, cascading trophic interactions are uncommon in species-rich terrestrial ecosystems (Murdoch 1966; White 1978; Hunter and Price 1992; Strong 1992; Polis and Strong 1996; Polis 1999). If anything, consumers are seen as factors that might change the behavior of their resources or the composition of resource guilds (Haukioja and Hakala 1975; Rhoades 1985; Leibold 1989, 1996; Abrams 1992, 1993, 1996; Pastor and Cohen 1997). In order to structure the discussion, the above view will be referred to as the defense diversity hypothesis (DDH). A diametrically opposite view of trophic dynamics was outlined by Elton (1927) and is more rigorously presented in the green world hypothesis (HSS) of Hairston et al. (1960). According to HSS, plants are vulnerable to folivores but are nevertheless seldom severely defoliated because the collective density of folivores (grazers, browsers, and folivorous insects) is regulated by the collective action of carnivorous and insectivorous animals. The hypothesis of exploitation ecosystems of Oksanen et al. (1981; to be referred to as EEH) converges with HSS with respect to productive areas (forests and their successional stages, productive wetlands). According to EEH, however, the control of folivorous endotherms by predators fails in unproductive ecosystems (tundras, high alpine areas, steppes, and semideserts), which are characterized by intense natural folivory.

Considering the time elapsed since the formulation of the two main alternatives, relatively few critical experiments have been conducted. Differences in approach and terminology have probably contributed to this situation. The DDH is focused on individual populations (e.g., Ehrlich and Birch 1967; Polis and Strong 1996), while HSS and EEH deal with guild-level dynamics of plants, folivores, and carnivores. These guilds have been referred to as trophic levels, which is conceptually debatable. Nev-

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ertheless, they are identifiable units, created by adaptational constraints and even reflected in taxonomy. Moreover, the conjecture that individual folivore populations display density-vague dynamics (Strong 1986) is entirely compatible with the conjecture of Hairston et al. (1960) that the collective standing crop of folivores is regulated by the collective action of carnivores.

The purpose of this article is, first, to explain why we regard both DDH and HSS as incomplete; second, to reanalyze the 1981 model of EEH with focus on endotherms, relaxing unnecessarily specific assumptions of the original model, and replacing graphics with explicit analysis; third, to provide an up-to-date review of relevant empirical evidence; and finally, to outline a research strategy on trophic dynamics.

The Productivity Connection

For us living at high latitudes, the shared point of departure of DDH and HSS—rarity of severe folivory—appeared unrealistic. In the early 1970s, we saw Norwegian lemmings destroy the moss cover of the tundra (Kalela 1971; Kalela and Koponen 1971). Simultaneously, subarctic forests were dying over enormous areas. The main trunks had been killed after recurrent defoliation by a geometric moth, and the basal recovery shoots were consumed by mammals (Kallio and Lehtonen 1975). Moreover, the profound impact of reindeer and gray-sided voles on the vegetation of the heathlands was easy to see (Oksanen 1978; Callaghan and Emanuelsson 1985; Oksanen and Virtanen 1995). Except for the insect outbreak, the strong impacts were not caused by exceptionally high numbers. Densities of microtine rodents were lower in typical tundra than in productive habitats (willow thickets), where no dramatic changes in vegetation were observed (Oksanen and Oksanen 1981). The winter reindeer density in the area where forests were changing to tundra was about three animals or 200–250 kg km⁻², excluding a period of mass starvation in the mid 1970s (L. Oksanen et al. 1995). This density is only twice as high as the average density of barren-ground caribou in northwestern mainland Canada (Crête 1999). Higher standing crops of cervids are commonplace at lower latitudes, but impacts on the vegetation are weaker, and mass starvation is unknown (Cederlund and Markgren 1987; Nygren 1987; Crête 1999). Fretwell's (1977) paper on the impact of primary productivity on trophic dynamics provided a potential solution for the arctic enigma of strong folivory but relatively low folivore densities. However, Fretwell's considerations contained logical gaps and opened more questions than they answered—as is typical for innovative contributions. To answer these questions has been the main theme of

our work during the past 2 decades, starting from the 1981 model of EEH.

The independent variable of EEH is potential productivity, defined as the maximum primary productivity of the habitat, when its nutrient pool is fully available, when leaf area index has reached its optimal value, but before the accumulation of heterotrophic stem tissues. In terrestrial ecosystems, this value depends primarily on evapotranspiration and secondarily on nutrient pool (Lieth 1975). Belowground production is included because grazing can dramatically change community-level allocation patterns between roots and shoots (Tilman 1988; Hambäck 1998). For herbaceous vegetation and low scrublands, actual net primary production is a good index for potential productivity. For woodlands, potential productivity should ideally be measured in the early stages of secondary succession. Values for mature forests must be corrected for respiration of stem tissues. In northern ecosystems, primary productivity is even influenced by indirect effects of secondary succession (Sirén 1955), which can be prevented (Zimov et al. 1995) or accelerated (Pastor and Naiman 1992; Pastor et al. 1993) by folivory. However, feedbacks caused by biotic factors cannot be included in the independent variable, which must derive from the properties of the physical environment.

The intention of the simple model of EEH was to produce a parsimonious hypothesis on trophic dynamics along broad biogeographical gradients, where potential productivity varies by orders of magnitude. Unfortunately, the 1981 model includes two unnecessary assumptions: logistic growth in plants and Type II functional response in consumers. Moreover, the team was divided on two central issues. The American part (S. Fretwell and J. Arruda) wanted to retain the integrity of trophic levels, whereas the Finnish part (L. Oksanen and P. Niemelä) preferred to restrict the model to endotherms (Oksanen et al. 1981, p. 257). Moreover, the Finns preferred to model secondary carnivory as diffuse intraguild predation (Oksanen et al. 1981, p. 250). The formal analyses presented in the paper were based on the American alternative. In the verbal part, the paper glided confusingly between the two views. Below, we will reanalyze the model, relaxing superfluous assumptions and consistently applying the Finnish approach. Unless otherwise stated, we will interpret the model as referring to the vegetation and to the guilds of folivorous and carnivorous endotherms. Extensions to other systems will be discussed separately.

A Generalized Version of the 1981 Model of EEH

The EEH builds on a plant equation in which the expansion of aboveground plant biomass is assumed to be an autocatalytic process; that is, growth rate depends on the

Table 1: Definitions of parameters and functions used in equations (1)–(3)

Expression	Definition
$r = \lambda_1 G$	The maximum per biomass unit expansion rate of plants.
$g(P, K)$	A function describing how this rate decreases with increasing plant biomass; g is assumed to have the following four properties: first, $g(0) = 1$; second, g is a monotonically decreasing function of P ; third, there is a $K > 0$, such as $g(K) = 0$; and finally, $K = \lambda_2 G$.
a	The searching efficiency of folivores.
$f(P)$	The impact of plant biomass on foraging efficiency and foraging motivation of folivores. The function is unspecified but assumed to have the following property: $af(P)P \rightarrow w$ when $P \rightarrow \infty$, where w is a positive constant.
m	The energetic costs of maintenance of folivores and their per capita mortality in the absence of forage.
k	The assimilation efficiency of folivores.
α	The searching efficiency of carnivores.
$\phi(H)$	The impact of folivore biomass on foraging effectivity and motivation of carnivores. The function is unspecified but assumed to have the following property: $\alpha\phi(H)H \rightarrow \omega$ when $H \rightarrow \infty$, where ω is a positive constant.
μ	The energetic costs of maintenance of carnivores and their per capita mortality in the absence of prey.
κ	The assimilation efficiency of carnivores.
i	The guild-level net loss imposed by intraguild predation at unit density of carnivores.

amount of foliage in the system. This assumption is debatable in a short time interval because plants can then sprout from subterranean reserves. However, EEH focuses on long-term, near-equilibrium dynamics, and in that context, growth rate must depend on leaf-area index. The other assumptions are as follows: First, the maximum growth rate of plants and the maximum amount of heterotrophic plant tissues that can be sustained are directly proportional to potential productivity. Second, the kinetics of trophic exploitation follow the principles of mass action (Rosenzweig 1971, 1973, 1977). Third, the vegetation and the guilds of folivorous and carnivorous endotherms can be treated as homogeneous units. Fourth, there is no population dynamically significant interference among folivores. And finally, encounters between carnivores have a fixed probability to lead to intraguild predation, which is a net loss on the guild level and can, thus, be modeled as a negative second-order term in the carnivore equation.

The above assumptions translate to the following differential equations:

$$dP/dt = rPg(P, K) - af(P)PH \quad (1)$$

$$= \lambda_1 Gpg(P, \lambda_2 G) - af(P)PH,$$

$$dH/dt = -mH + kaf(P)PH - \alpha\phi(H)HC, \quad (2)$$

$$dC/dt = -\mu C + \kappa\alpha\phi(H)HC - iC^2, \quad (3)$$

where P , H , and C are the standing crops of plants, folivorous endotherms, and carnivorous endotherms, respectively, and G is potential productivity. Definitions of functions and parameters are provided in table 1. Notice that the functions for density dependence in plants and func-

tional responses in consumers are unspecified, except that biologically reasonable boundary conditions are assumed. For instance, we assume the existence of λ_2 such that $g(\lambda_2 G) = 0$, and we assume the existence of the saturation constants w and ω such that $af(P)P \rightarrow w$ when $P \rightarrow \infty$ and $\alpha\phi(H)H \rightarrow \omega$ when $H \rightarrow \infty$.

The equations for 0 isoclines (actually: isosurfaces) for plants, folivores, and carnivores can be derived from equations (1)–(3) by setting the time derivatives equal to 0, which yields the following equations for plant (4), folivore (5), and carnivore (6) isoclines, respectively:

$$H = \frac{r g(P, K)}{a f(P)} = \frac{\lambda_1 G g(P, \lambda_2 G)}{a f(P)}, \quad (4)$$

$$C = \frac{kaf(P)P - m}{\alpha\phi(H)}, \quad (5)$$

$$H = \frac{\mu + iC}{\kappa\alpha\phi(H)} \Leftrightarrow C = \frac{\kappa\alpha\phi(H)H}{i} - \frac{\mu}{i}. \quad (6a)$$

The assumption of intraguild predation makes the technical analysis more complicated than in the 1981 model. However, the saturation of the functional response of the folivores and the consequent bending of the folivore isocline largely eliminates the impact of intraguild predation on equilibrium biomass patterns. For the purpose of predicting biomass patterns, we can thus set $i \approx 0$, which simplifies the expression for carnivore isocline to

$$H^* \approx \frac{\mu}{\kappa\alpha\phi(H^*)}. \quad (6b)$$

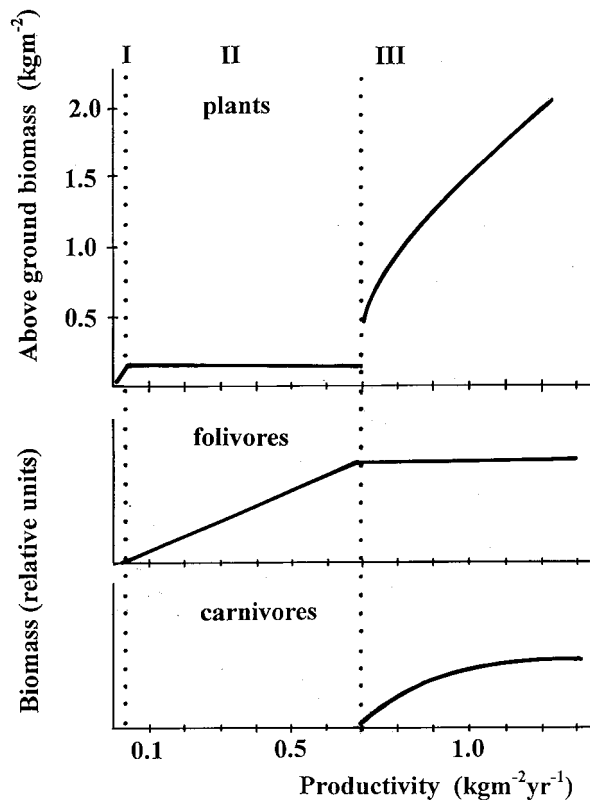


Figure 1: Patterns in aboveground plant biomass, in biomass of folivorous endotherms, and in biomass of carnivorous endotherms predicted by EEH, assuming functional responses that saturate at moderate resource densities. Roman numerals refer to predicted zones with different trophic dynamics (I, one-link dynamics; II, two-link dynamics; III, three-link dynamics). Patterns at the transition from zone II to zone III depend on specific assumptions. The perfectly flat relationship between folivore biomass and potential productivity in zone III presupposes that there is no intraguild predation. Intraguild predation will create a weak, positive relationship between folivore biomass and potential productivity, even in the beginning of zone III, where folivores are not saturated.

In the absence of carnivores, folivores act purely as predators of plants and equation (5) is reduced to

$$P^* = \frac{m}{kaf(P^*)}. \quad (7)$$

If potential primary productivity is so low that $\lambda_2 G = K < P^*$, folivorous endotherms will be absent. In these “one-link ecosystems” the scanty plant biomass is predicted to be at carrying capacity (fig. 1, zone I). When $K > P^*$, we enter “two-link ecosystems,” where equilibrium plant biomass will be fixed at P^* (fig. 1, zone II). In corresponding seasonal systems, late-summer biomasses will increase with increasing potential productivity, as res-

ident endotherms cannot track the seasonal pulse of plant growth (L. Oksanen, unpublished data).

Equilibrium biomass of folivorous endotherms is obtained by substituting $P = P^*$ into equation (4) so that

$$H = \frac{r g(P^*, K)}{a f(P^*)}. \quad (8)$$

Recall that $f(P^*)$ is constant and that $g(P^*, K) \approx 1$ when $P^* \ll K$. Moreover, $r = \lambda_1 G$. Thus, the equilibrium biomass of folivorous endotherms is predicted to increase approximately linearly with increasing primary productivity in the productive end of zone II. For less productive systems, the pattern depends on the forms of $g(P)$ and $f(P)$ functions. In systems where folivores have Type II functional response (e.g., because all plant biomass is available for folivores), increasing potential productivity is destabilizing (Rosenzweig 1971) and leads to violent folivore-plant cycles. Systems with two-link trophic dynamics can even be destabilized by seasonality, especially if the dominating folivores have high reproductive capacity (L. Oksanen 1990a).

The presence of a carnivore guild requires that the folivore density at the folivore-plant equilibrium (eq. [8]) exceeds H^* (see eqq. [6a], [6b]), which yields inequality

$$\frac{\mu}{k\alpha\phi(H^*)} < \frac{r g(P, K)}{a f(P)} = \frac{\lambda_1 G g(P, \lambda_2 G)}{a f(P)}. \quad (9)$$

Even with an unstable folivore-plant equilibrium, a carnivore-folivore-plant equilibrium emerges as an alternative attractor at potential productivity only slightly higher than implied by inequality (9) (Rosenzweig 1973; Abrams and Roth 1994a). Systems without mobile predators can remain trapped in the cyclic folivore-plant attractor (Abrams and Roth 1994a, 1994b). However, where mobile avian predators abound—as they seem to do in the boreal zone (Korpimäki and Norrdahl 1989, 1991a, 1991b; Hörnfeldt et al. 1990; Norrdahl and Korpimäki 1996)—their impact will push the system into the domain of attraction of the carnivore-folivore-plant equilibrium.

When the threshold represented by inequality (9) is passed, we enter the green worlds of “three-link ecosystems” (fig. 1, zone III). The standing crop of folivores is predicted to stay put at $H = H^*$, and plant biomass is predicted to increase with increasing potential productivity. At the transition, specific assumptions count and singularities may emerge. With further increase in potential productivity, the predicted response of aboveground plant biomass to increasing potential productivity is almost linear because $P^* \approx K = \lambda_2 G$.

The predicted collective response of carnivores to en-

richments can be studied by substituting $H = H^*$ into the equation of the herbivore isocline (eq. [5]), which yields

$$C = \frac{kaf(P)P - m}{\alpha\phi(H^*)}. \quad (10)$$

The denominator is a constant. The term $af(P)P$ in the numerator is the functional response of the folivores, which approaches the saturation constant, (w), when plant biomass increases. In systems with high plant biomasses, the right-hand side of equation (10) consists entirely of constants. Hence, the predicted relationship between primary productivity and carnivore standing crop is asymptotic. In highly productive terrestrial ecosystems, increased primary productivity should thus be retained by plants and, in the end, funneled into the detritus web.

The stability of the enriched three-link ecosystems depends on details. With Type II functional response, the equilibrium will be destabilized by enrichment (Abrams and Roth 1994a), whereas it can remain stable if predators have Type III functional response, supposedly typical for generalists (Andersson and Erlinge 1977; Hanski et al. 1991; Hanski and Korpimäki 1995). However, this requires nonoptimal foraging (preferred prey are ignored at low densities) and nondepletable alternative resources, which is inconsistent with EEH and debatable even in principle. Generalists exploiting different species of folivores will only synchronize guild-level dynamics. A more plausible source of stability is provided by intraguild predation, imposing direct density dependence on the predator guild (Wollkind 1976). Conversely, setting $i = 0$ in equation (6a), a mechanism for sustained carnivore-folivore cycles is obtained. This is plausible for systems dominated by small carnivores, which are in the role of victims in intraguild predation and should, thus, display *laissez-faire* dynamics in areas where they and their prey are protected against larger carnivores. (Unable to protect their prey against larger competitors, they are unlikely to have evolved territorial defense of resource supply against conspecifics, see Oksanen et al. 1985). In the boreal zone, such protection is offered by the long-lasting snow cover (Hansson and Henttonen 1985). Occurrence of cycles of small predators and their prey in productive, boreal habitats is, thus, a straight forward consequence of the basic premises of EEH, combined with the splitting of the folivore and carnivore guilds by the impact of the long, snowy winter.

In the simple model of EEH, the three-link trophic cascade is predicted to embrace all plants growing in productive terrestrial ecosystems. A different variant on the same theme was proposed by Oksanen (1992) by including evolutionary trade-offs between capacity to exploit low-quality forage and ability to escape predation. In this evolutionary variant of EEH, the parameter α (searching ef-

iciency of carnivores) decreases along gradients of increasing potential productivity because of increasing elusiveness of folivores. Hence, folivore standing crop (H^*) will increase monotonically with increasing potential productivity. Due to the trade-offs, the least palatable plants are predicted to be lifted outside the trophic cascade in productive areas. Removal of carnivorous endotherms is predicted to first lead to decimation of palatable plants, then to increased standing crops of unpalatable plants. First in evolutionary timescale or after the invasion or introduction of folivores from unproductive areas with two-link trophic dynamics, the standing crops of all plants should be reduced to the P^* of the simple model of EEH. Both variants of EEH derive from the same approach, but they are nevertheless so different that they must be regarded as two separate hypotheses.

In the 1981 model of EEH, the spatial scale of the model is not specified. Holt (1984, 1985) discovered that the predictions of EEH cannot hold in small-scale habitat complexes with suboptimal habitat selection. Inspired by her snow-tracking results, T. Oksanen (Henttonen et al. 1987; Oksanen and Henttonen 1996) extended the argument to embrace even three kinds of optimal behavior, differing from the Ideal Free model of Fretwell (1972) and from Charnov's (1976) marginal value theorem. First, socially inferior individuals and individuals belonging to the smallest species in the guild must weigh the advantages of high prey density against the risk of aggression and intraguild predation (T. Oksanen 1990). Second, all predators become habitat generalists in the crash phase of the prey cycle, when between-habitat differences in prey density disappear (T. Oksanen et al. 1992a). Third, it pays to attack a prey encountered during transit movements (T. Oksanen et al. 1992b). Hence, EEH can be expected to apply to trophic dynamics in the dominating habitat of the landscape and, with minor reservations, to dynamics in more productive habitats. Conversely, if a patch of barren habitat lies in a productive landscape or if it is juxtaposed at a rich marine environment (Polis and Hurd 1996), dynamics in the barren habitat will be driven by spillover predation.

Realism of EEH along Gradients from Cold Barrens to Warm and Productive Regions

Biomass Patterns in Plants

Plant biomass patterns predicted by EEH (fig. 1) clearly diverge from the null hypothesis of linear relation between potential productivity and aboveground standing crop. According to EEH, there is a wide productivity interval (fig. 1, zone II) where the regression of aboveground plant biomass versus potential productivity is flat (annual minima) or has shallow slope (annual maxima).

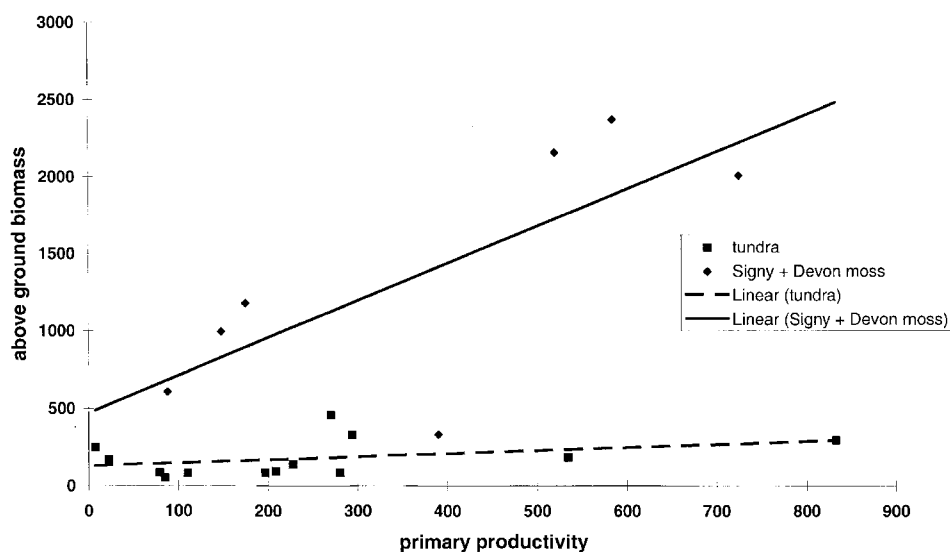


Figure 2: Relation between aboveground plant biomass (gm^{-2}) and annual primary productivity ($\text{gm}^{-2} \text{yr}^{-1}$) in the tundra areas with folivorous endotherms (Barrow, Alaska; Hardangervidda, Norway; and ridge and slope sites on Devon Island, Nunavut) and in the polar areas without folivorous endotherms capable of using the site in winter (Signy, Maritime Antarctic, and mossy bottomlands of Devon Island). Regression for the tundra is $y = 127 + 0.20x$, $R^2 = 0.135$, $n = 13$. Regression for the folivore-free polar areas is $y = 470 + 2.41x$, $R^2 = 0.544$, $n = 7$.

Moreover, there must be a sharp transition to a steep, positive relation (zone III). This prediction is corroborated by arctic-boreal data (Oksanen 1983; Oksanen et al. 1992), by alpine-subalpine data (Körner 1999, pp. 253–255) and even by global biomass data (Begon et al. 1996, fig. 18.5). However, the prediction is not unique for EEH. A roughly similar pattern is predicted by the hypothesis that only plants with small shoots can tolerate the environmental stresses of arctic, alpine, and arid environments (Grime 1979) and by the hypothesis that, in unproductive environments, plants compete primarily for soil resources (Walter 1964; Tilman 1988). In principle, the pattern could even be caused by a shift from stable to cyclic folivore-plant dynamics (Abrams and Roth 1994*b*), if the vegetation could recover in a time-scale shorter than the period of the cycle. The value of corroboration, thus, hinges on the following additional predictions: first, the flat relationship depends on the presence of folivores; second, the sharp change of biomass trend depends on the presence of carnivores; third, the pattern does not depend on the accumulation of stem wood or, fourth, on change from stable to cyclic dynamics in folivores.

To test the first additional prediction, we have compared biomasses of typical tundra habitats (Kjelvik and Kärenlampi 1975; Wielgolaski 1975; Bliss 1977; Miller et al. 1980) to equally unproductive polar habitats without folivorous endotherms. The maritime Antarctic (Collins et al. 1975)

provides such points of reference, as do the mossy bottomlands in those high Arctic areas where moss-eating mammals do not occur (e.g., northern Devon Island; Bliss 1977). Subantarctic islands, in turn, provide information relevant for the second and third additional predictions. Their productivities correspond to or even exceed the productivities of boreal forests, but the vegetation—grasslands, herbfields, and semiherbaceous communities—is totally different. One island—South Georgia—used to have a variant of three-link trophic structure with introduced reindeer hunted by whalers (Lewis Smith and Walton 1975). Another—Macquarie—has folivorous endotherms (introduced rabbits) but no predators (Jenkin 1975). To avoid any biases in favor of EEH, we have excluded stem wood from boreal biomasses (sources: Mälkönen 1974, 1977; Kjelvik and Kärenlampi 1975; Paavilainen 1980; Albrektsson and Lundmark 1991). For moss communities, only the top part of the brown-moss biomass has been regarded as truly living (the ratio of green to live brown biomass is based on Vitt and Pakarinen 1977). The Arctic-Antarctic biomass patterns are presented in figure 2. For areas with folivorous endotherms, the relation between biomass and productivity is flat, whereas the folivore-free habitats are characterized by a positive relation with a steep slope. In figure 3, the productivity gradient is extended to embrace boreal and subantarctic habitats. In these areas, the biomass-productivity relation is positive and has a steep slope, provided that there is

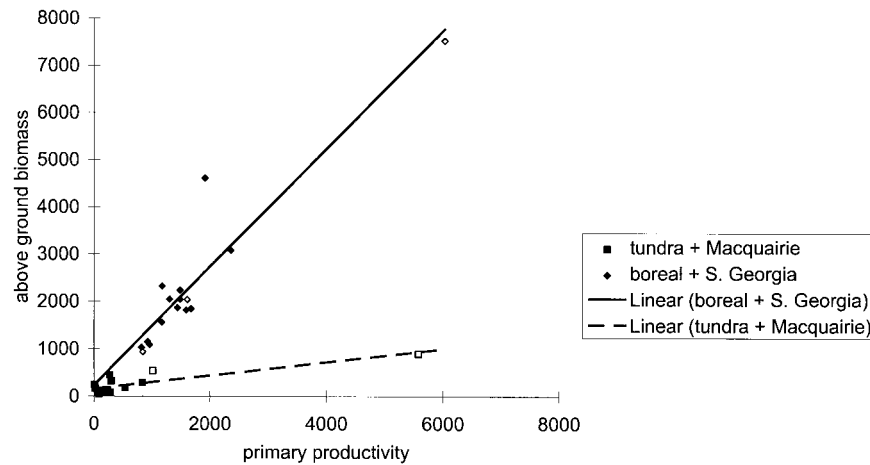


Figure 3: Relation between aboveground plant biomass (gm^{-2}) and annual primary productivity ($\text{gm}^{-2} \text{yr}^{-1}$) in areas where EEH predicts folivorous endotherms to be resource-limited and the vegetation to be grazer-controlled (unproductive arctic areas with a complete guild of herbivorous endotherms plus the predator-free subantarctic island Macquairie) and in areas where folivores are predicted to be predator-controlled and plant biomass is predicted to be close to carrying capacity (low-arctic and boreal Fennoscandian habitats with annual primary productivity exceeding $700 \text{ gm}^{-2} \text{ yr}^{-1}$ plus the subantarctic South Georgia before the reindeer eruption). Filled symbols refer to Arctic and boreal data points, open symbols to subantarctic data. Regression for tundra + Macquairie is $y = 156 + 0.14x$; $R^2 = 0.711$, $n = 15$; regression for boreal habitats + South Georgia is $y = 236 + 1.25x$; $R^2 = 0.870$, $n = 16$.

predation or hunting. In the data set obtained combining the arctic tundra and the predation-free Macquairie, the relation is significantly positive, too, but the slope is even more shallow than indicated by the Arctic data alone. Temporal changes are consistent with spatial patterns. On mossy tundra, aboveground plant biomass has increased threefold during 15 yr of grazer exclusion (Virtanen 2000). On subantarctic islands, the introduction of rabbits and the cessation of reindeer hunting have resulted in the total destruction of productive, biomass-rich plant communities (Werth 1928; Leader-Williams 1988). For the fourth additional prediction, see the sections on trophic dynamics.

Notice that many arctic communities are dominated by relatively unpalatable plants. Tannin-loaded, evergreen dwarf shrubs and lichens with high concentrations of lichenic acids abound on ridges (Kalliola 1939; Dahl 1957; Haapasaari 1988; Oksanen and Virtanen 1995), and bottomlands are dominated by mosses, regarded as inedible as a result of lignin-like substances in their cell walls (Prins 1982). Moreover, there is much scatter in the biomass-productivity relation of figure 2 (see also Wegener and Odasz 1998), indicating that plant defenses influence the position of the folivore isocline. However, the defenses are not absolute. Even the unpalatable mosses and cushion plants are eaten by brown/Norwegian lemmings and rock ptarmigans, respectively. All plants contain reduced carbon and nutrients. Where the fitness of folivores depends on their ability to handle low-quality forage, evolution ap-

pears to create animals with a sufficiently large and complex digestive system to handle even the poorest forage.

Biomass Patterns in Folivores

For unproductive ecosystems (fig. 1, zone II), EEH predicts that the standing crop of folivorous endotherms rises linearly with increasing potential productivity. This prediction has, however, little diagnostic value. The critical prediction is the flat relation between potential productivity and folivore biomass in productive ecosystems (fig. 1, zone III). For data sets including both categories of systems, the regression of folivore biomass against potential productivity should have a positive slope and a positive y -intercept. Moreover, a logarithmic regression with a built-in flattening at high x values should fit the data better than a linear regression. Notice that these predictions cannot be tested with logarithmically transformed data. Thus, the work of McNaughton et al. (1989) cannot be regarded as a critical test of EEH. The reanalysis by Moen and Oksanen (1991) is a critique of McNaughton et al. (1989) rather than a test of EEH. The raw data are presented in figure 4. For the temperate data points, the premise of reasonably natural carnivore-folivore dynamics is not even approximately satisfied (Crête 1999), and in several temperate studies, endotherms have not been included at all. As temperate data points are nonrandomly distributed along the productivity axis, there is a risk of spurious patterns. The only

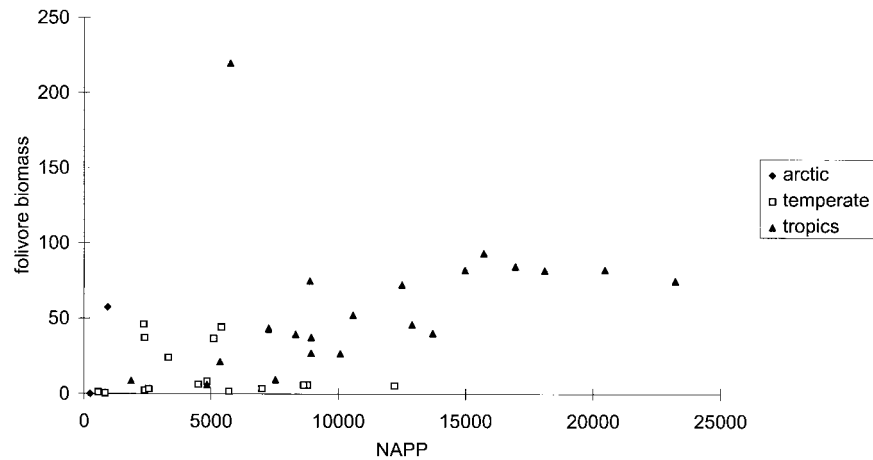


Figure 4: Folivore biomasses (kJm^{-2}), plotted against net aboveground productivity (NAPP, $\text{kJm}^{-2} \text{yr}^{-1}$) in the material of Moen and Oksanen (1991). The data were derived from the references of McNaughton et al. (1989). Units: kJm^{-2} for folivore biomass and $\text{kJm}^{-2} \text{yr}^{-1}$ for net aboveground productivity. With an allocation ratio of 1 : 3 between aboveground and belowground organs, the productivity threshold of $700 \text{ gm}^{-2} \text{yr}^{-1}$ corresponds to NAPP of $3,500 \text{ kJm}^{-2} \text{yr}^{-1}$. Excluding temperate data, the linear regression for the biomass-productivity regression is $y = 24.7 + 0.0029x$, $R^2 = 0.152$. The logarithmic regression is $y = -91.5 + 16.335 \log x$, $R^2 = 0.159$, $n = 25$. For the data points above the above-productivity threshold, the regression is $y = 36.7 + 0.0020x$, $R^2 = 0.052$, $n = 21$.

firm conclusion that we can draw from these data is that the highest folivore biomasses are remarkably constant within different productivity intervals. Regressions computed without temperate data are consistent with EEH, but even this data set contains so many questionable points that the corroboration has little value.

For big folivores, more dependable material has been recently compiled by Crête (1999) and Crête and Manseau (1996). The biomasses of cervids increase along the latitudinal productivity gradient from high-arctic to low-arctic Canada. In the boreal zone, the increasing trend stops. Close to the Canada-U.S. border, where wolves become rare, cervid biomasses increase again. Within the currently wolf-free United States, cervid biomasses increase profoundly with increasing potential productivity. These spatial patterns conform to the predictions of the simple model of EEH. The ongoing reestablishment of wolves in the United States provides a rare opportunity to make predictions about the more distant future. According to EEH, the current high cervid biomasses of the productive southeastern states will be reduced to the level prevailing in the Canadian taiga when wolves reach resource limitation.

Patterns in Occurrence and Abundance of Carnivorous Endotherms

The EEH differs from Fretwell's (1977) verbal food chain hypothesis, where carnivores are assumed to form a continuum from carrion feeders to efficient killers and food

chain length is a subtle issue. In EEH, trophic guilds are discrete and the equilibrium standing crop of carnivorous endotherms is predicted to be 0 in unproductive ecosystems (fig. 1, zones I and II). Scavengers can be present everywhere because they can have essentially lower costs of maintenance than true carnivores. The EEH thus requires that the difference between scavengers and carnivores be easy to infer from natural history, including social organization (e.g., lone wolves are scavengers, wolf packs are carnivores). In EEH, the idea of carnivores being physically present but dynamically absent can only refer to systems with a locally unstable folivore-plant equilibrium, generating violent folivore-plant cycles. In these systems folivore peaks are likely to cross the carnivore isocline, creating a niche for outbreak croppers. These "visiting carnivores" should be characterized by extreme nomadism or by a strategy where outbreaks are used for breeding, while survival resources are in other systems.

Studies on terrestrial carnivore communities in the Arctic have been reviewed by Oksanen et al. (1996). The bottom line is that the inclusion of terrestrial carnivores in high-arctic food webs reflects considerable stretching of criteria for presence. For instance, only three stray wolves have been recorded by the Canadian International Biological Program (IBP) team along the entire northern coast of Devon Island. Stoats have been only intermittently present and only in trace numbers. Jaegers prey primarily on invertebrates, eggs, and young birds. The only endotherm that is consistently present and that uses other endotherms as its primary resources is the scavenging arctic fox (Pattie

1977; Riewe 1977a, 1997b). In middle-arctic landscapes characterized by strong lemming outbreaks, jaegers and snowy owls are periodically numerous and do eat lemmings (Batzli et al. 1980). However, these carnivores are typical outbreak croppers, which roam around in the Arctic or move between the tundra and the ocean. In the low Arctic, the predominating barrens are still, by and large, carnivore-free, but the most productive habitats harbor a diverse community of mammalian and avian carnivores (Oksanen and Oksanen 1992; Oksanen et al. 1996, 1997, 1999). Carnivores, thus, emerge as persistent community members in the habitats where the productivity threshold of $700 \text{ gm}^{-2} \text{ yr}^{-1}$ is exceeded, where the biomass trend changes, and where the plant community is for the first time dominated by erect shrubs. The gradient from low-arctic to temperate habitats is characterized by increasing density and diversity of carnivorous endotherms (Erlinge et al. 1983; Korpimäki and Norrdahl 1989, 1991a, 1991b; Hörnfeldt et al. 1990; Hanski et al. 1991; Korpimäki et al. 1991).

Trophic Dynamics in Unproductive Tundra Areas

The EEH predicts that the plant cover of the tundra is locked in a strong, dynamical interaction with folivorous endotherms. Even this prediction is amply corroborated. During the extended low phase of Norwegian lemmings from 1971 to 1977, moss biomasses of snowy tundra habitats increased by an order of magnitude (Kyllönen and Laine 1980; Oksanen 1983). In crash winters, these habitats are denuded (Tihomirov 1959; Batzli et al. 1980; Oksanen and Oksanen 1981; Černjavskij and Tkačev 1982; Moen et al. 1993). Moreover, the outbreaks of lemmings in arctic and alpine barrens follow the predicted time trajectory of a predator—with long periods of low numbers and sharp peaks, ending in abrupt and very deep crashes (Batzli et al. 1980; Oksanen and Oksanen 1992; Framstad et al. 1993; Ekerholm et al. 2000; Turchin et al. 2000). Even the strong dispersal tendency of lemmings during population peaks (Oksanen and Oksanen 1981; Henttonen and Kaikusalo 1993) fits to the behavior of other species adapted to periodic discrepancy between numbers and food supply (Kallela 1949). Daring cliffs, waves, and hostile habitats gives them a chance. Suicide is committed by lemmings staying behind.

The strength of the interaction between the relatively stable ungulate populations and the tundra vegetation can be inferred from two kinds of data. The relatively recent observational studies known to us bear witness to total resource limitation in arctic ungulates (Reimers et al. 1980; Thomas and Edmonds 1983; Caughley and Gunn 1993; Tyler 1993; Crête and Manseau 1996). The strength of the interaction can be inferred from spatial differences in the

vegetation. In areas without reindeer (caribou), dry, low-arctic tundra heaths are covered by continuous, 10–20 cm thick “reindeer moss” carpets (Du Rietz 1925; Dahl 1957). When grazed by reindeer, similar sites have a thin, lichen-moss cover, dominated by entirely different species (Kalliola 1939; Oksanen 1978; Haapasaari 1988; Oksanen and Virtanen 1995). The differences in space correspond to the changes observed in the Canadian low Arctic after the recovery of the barren-ground caribou (Crête and Huot 1993; Crête and Manseau 1996).

The intensity of the folivore-plant interaction of the tundra has been demonstrated experimentally, too. Exclusion of folivorous endotherms has initiated dramatic changes in the vegetation, the winners being shrubs and broad-leaved herbs in relatively benign habitats and robust cryptogams in more extreme sites (Oksanen 1988; Oksanen and Moen 1994; Virtanen et al. 1997a; Moen and Oksanen 1998; Virtanen 1998, 2000). The final result for coastal arctic areas is seen on the grazer-free islands in the Norwegian arctic, where sheltered and nutrient-rich sites support herbfields and less favorable sites are occupied by massive moss banks. Typical tundra does not exist at all (Virtanen et al. 1997b). The primeval states of the Antarctic and subantarctic islands discussed above are variants on the same theme.

The strength of the folivore-plant interaction on the tundra is not appreciated by all arctic ecologists. Bazely and Jeffries (1997) and Jeffries et al. (1994) regard vertebrate herbivory as generally unimportant in the Arctic, except for salt marshes grazed by snow geese. However, their arguments refer to the fraction of primary production consumed by folivores, which reflects their ability or inability to track plant production rather than the intensity of winter grazing. Moreover, they emphasize the IBP data from the early 1970s, when the muskoxen herd in question was in a period of strong increase (Hubert 1977). In the context of North America, we must remember that, even three decades ago, arctic ungulates were regarded as threatened species as a result of overhunting (Tener 1965; Kelsall 1968). Hence, old North American data are not representative for steady state dynamics.

Trophic Dynamics in Productive Ecosystems at High and Middle Latitudes

Entirely different dynamics are encountered in the most productive low-arctic habitats and in the boreal zone. Small-mammal cycles are wave like, corresponding to the time trajectory of a prey in a predator-prey limit cycle (Krebs 1964; Henttonen et al. 1987; Korpimäki and Norrdahl 1989, 1991a, 1991b; Hanski et al. 1991, 1993; Korpimäki et al. 1991; Krebs et al. 1992; Oksanen and Oksanen 1992; Hanski and Korpimäki 1995; Hanski and Henttonen

1996; Turchin and Hanski 1997; Turchin et al. 2000). The cross-continental difference in the cycling species (weasels and voles in Europe, lynxes and hares in Canada) conforms to the implication of EEH that the combination of high potential productivity and low intensity of intraguild predation leads to carnivore-folivore cycles. In northern Europe, the crusty snows created by recurrent invasion of Atlantic warm fronts do not protect only voles against generalists and avian predators (Hansson and Henttonen 1985), even weasels enjoy the same protection. The North American geography creates entirely different winter conditions. The impact of Pacific warm fronts is restricted to the western mountains, where weasel-vole cycles occur (Fitzgerald 1977). The rest of North America gets snow primarily with cold fronts. The Canadian taiga is characterized by powdery snow, which leaves weasels exposed to intraguild predation but protects the light, large-footed lynxes against wolves.

By arctic standards, the impact of folivorous mammals on boreal and temperate vegetation is light, except on especially grazing-sensitive plants (e.g., tree seedlings and shrubs, Ericson 1977; Hansson 1985; Oksanen and Ericson 1987; Ericson et al. 1992; Ostfeld and Canham 1993) and the exclusion of folivores makes little difference for the vegetation (Oksanen 1988; Oksanen and Moen 1994; Moen and Oksanen 1998). Conversely, density reductions of carnivorous endotherms have resulted in remarkable increases in survival rates of small folivores (Krebs et al. 1995; Norrdahl and Korpimäki 1995; Reid et al. 1995; Korpimäki and Krebs 1996; Klemola et al. 1997; Korpimäki and Norrdahl 1998). Predator enclosures and predation-free islands are characterized by very high folivore densities and dramatic grazing impacts on the vegetation (Linnman 1971; Ottoson 1971; Soikkeli and Virtanen 1975; Angerbjörn 1981; Häkkinen and Jokinen 1981; Pokki 1981; Oksanen et al. 1987; Hambäck and Ekerholm 1997; Klemola et al. 2000a, 2000b). Provision of natural food (fertilization leading to increased browse production) does not have any consistent effect on folivore densities, whereas folivores have responded positively to the provision of high-quality food (Henttonen et al. 1987; Krebs et al. 1995). Just giving more food should not help predation-controlled folivores. Conversely, provision of high-quality food allows reduced foraging times and increased vigilance (Abrams 1984; Brown 1992), which reduces the searching efficiency of predators (the parameter α in eq. [3]), thus increasing H^* (see eq. [6b]).

As pointed out by Polis (1999), the widespread extirpation of big predators represents an equivalent of predator-removal experiments for ungulates, provided that man has not himself taken the predator's role. An instructive example is a feral reindeer population established by

stray individuals south of the limit of reindeer husbandry in Sweden. In the absence of predation and hunting, the herd erupted, wreaking havoc on the vegetation (Höglund and Eriksson 1973). Similar scenarios have been displayed on boreal islands where predators have been absent or rare (Potvin and Breton 1992; McLaren and Peterson 1994) and in East African preserves, when poaching of folivorous mammals has declined but the design of the preserve has not allowed full protection of carnivores (Talbot 1965; Curry-Lindahl 1968; Vesey-Fitzgerald 1973). The domestication of folivorous mammals and their subsequent protection against predation is a variation on the same theme. In all parts of Eurasia, where climate has allowed extensive year-round, out-of-doors grazing, enormous forest areas have been replaced by secondary grasslands and heathlands. Plant ecologists are in total agreement about the pivotal role domesticated grazers and browsers in these habitat changes (Cajander 1916; Walter 1968; Gimingham 1972; Crawley 1983;).

Trophic Dynamics and Guild Structure in Arctic and Boreal Folivorous Endotherms

Competition theory predicts that resource-limited folivores should be primarily segregated along the axis of food and habitat use in the limiting season. In arctic and alpine areas with uneven snow distribution, this accounts for the coexistence of rodents exploiting snowy habitats and ungulates using upland habitats. Otherwise, body sizes should converge toward an optimal compromise between absolute and relative energy needs. This is what we observe in the Arctic. Rock ptarmigans exploit cushion plants and trailing woody plants on windblown ridges. Reindeer (caribou) forage on lichens and winter-green graminoids of upland habitats. Muskoxen, using similar winter habitats, tend to be geographically segregated from reindeer/caribou, in spite of the differences in their diets. Collared lemmings (in Russia and North America) or grey-sided voles (in Fennoscandia) use dwarf shrubs. Brown or Norwegian lemmings forage on graminoids and mosses in snowy bottomlands. Users of the same winter habitat and resource are allopatric, and there is intense competition even between folivore species with rather different winter niches (Morris et al. 2000).

Coexistence under apparent competition allows convergent food and habitat use but requires divergence along axes relevant to predator-prey interaction (Holt 1977). Body size is such a niche dimension because each carnivore can only effectively exploit a restricted range of prey sizes. Divergence along the body size axis is indeed pronounced in the boreal zone and in the most productive low-arctic habitats. Redback voles, grouses, hares, deer, and moose exploit the same browse but are food for different pred-

ators. The body size diversity of boreal folivores had been even more pronounced before the mass extinctions in the end of the Pleistocene (Kurtén 1971). The timing of North American extinctions correlates with the invasion of hunting tribes (Alroy 1999), and even in the Old World, development of human hunting techniques is a plausible explanation for the disproportionate fatality of the most recent transition from glacial to interglacial conditions. In apparent competition, success is determined by the ratio of reproductive rate to loss rate (Holt 1977; Armstrong 1979). When loss rates inflicted by the new generalist started to increase, megaherbivores were doomed by their low reproductive rates.

The consequent reduction of size diversity can largely account for the successes of EEH in explaining current patterns in trophic dynamics. In the past, increasing predation pressure probably caused major shifts in body size diversity, and the guilds of folivorous endotherms were anything but homogeneous blocks. Between the tundra proper, with clean, two-link dynamics, and forests with, three-link, trophic dynamics, there was probably a broad zone where small- and medium-sized folivorous mammals were predation controlled, whereas the larger ones were resource limited. Within this zone, grazing and browsing pressure and the accompanied mechanical injury was probably periodically intense, keeping the landscape savanna-like, as a productive grassland (see Zimov et al. 1995) with only patches of woody vegetation, as shown in the reconstructions of Kurtén (1969).

Applicability of EEH to Other Systems

Arid Environments

The logic of EEH does not depend on the ultimate cause of differences in potential productivity, but the factor controlling productivity may also influence the realism of the critical premises of EEH. As for the gradient from temperate and tropical forests to moderately arid plains and semideserts, we cannot see such confounding interactions. The case of real deserts is, however, different. Many desert plants pass the unfavorable season as seeds (Walter 1968), and the high quality of seeds implies a huge increase in the conversion efficiency of plant biomass to assimilated energy (the constant k in eq. [2]). The high efficiency at which primary production is channeled to secondary production in annual-dominated deserts allows even the build-up of relatively dense populations of carnivorous endotherms, posing high predation risks to desert rodents (Kotler et al. 1992). As for desert ungulates, we have another problem. A central premise of EEH is that trophic dynamics obey the principle of mass action, which presupposes random search. In deserts, where water is a lim-

iting resource, this premise is violated. A predator knowing the locations of water holes can sit there and wait for the prey, as leopards seem to do in the Negev (B. Kotler and J. Brown, personal communication). Rather than indicating one-link trophic dynamics, the striking vegetational characteristics of real deserts seem to reflect the return of three-link trophic dynamics.

Dynamics of Folivorous Insects

Due to their low mobility, the larvae of folivorous insects should be vulnerable to their natural enemies, and the same applies to the immobile pupae (Hanski 1987; Tanshuanpää et al. 1999). The experiments performed so far tell that reduced predator density normally leads to increased densities of folivorous insects and increased levels of damage in palatable plants (Schmitz et al. 2000; see also Atlegrim 1989; Spiller and Schoener 1990, 1994; Schmitz 1992, 1994, 1997; Marquis and Whelan 1994; Dial and Roughgarden 1995; Uriarte and Schmitz 1997). However, the observed magnitudes of cascading effects have been modest. The main reason for ambiguity is the short time-scale of these experiments. We look forward to experiments in which plants from natural habitats could be enclosed with their folivores in an enemy-free space, large enough for mating and oviposition, for several generations of folivores. Thus far, we have had to use circumstantial evidence, which to our judgment supports the conjecture of trophic cascades. Strong circumstantial evidence for cascades has been obtained, even in the context of gall-builders and root-feeders, which are maximally protected against parasitoids and predators and which are maximally exposed to the chemical environment of the plant (Strong and Larsson 1994; Strong et al. 1996). The relevance of the energy constraint of EEH is less clear. Some data are supportive of EEH, even in the context of folivorous insects (Frazer 1997; Frazer and Grime 1997), while others are not (Oksanen et al. 1997).

Dynamics in Pelagic Systems

Pelagic systems have played a key role in establishing the idea of trophic cascades (Carpenter et al. 1985; Carpenter and Kitchell 1988). Likely contributing factors are the easiness of manipulating trophic structures in small lakes and the short generation times of plankters. This need not imply that cascades were more pronounced in pelagic systems than in systems where plants are more long-lived. Defense against herbivores is probably easier and cheaper for phytoplankters than for terrestrial plants because linking algal cells in long chains amounts to efficient defense against zooplankters (McQueen et al. 1986; Leibold 1989, 1996; Strong 1992; Leibold et al. 1997). The ability of

filamentous algae to act as “nutrient sponges” further complicates trophic dynamics (Murdoch et al. 1998). On the other hand, planktivores selectively remove large *Daphnias*, which have relatively good ability to break the filaments (Brooks and Dodson 1965; Hansson 1992). Hence, indirect impacts of trophic cascades can contribute to the apparent inedibility of filamentous algae (Persson et al. 1996).

The ecoenergetic efficiencies of aquatic organisms are high (Humphreys 1979), and we are not aware of the existence of lakes too unproductive to support planktivores. The interesting part of EEH for pelagic ecosystems is the transition from three- to four-link trophic dynamics. In this context, the ontogenic omnivory of piscivores complicates dynamics. The planktivorous prey compete with juvenile piscivores, and adult piscivores prey on their own young. Thus, productive lakes may collapse back to three-link dynamics as a result of the self limitation imposed by cannibalism on piscivores and as a result of competition between planktivores and juvenile piscivores (Persson et al. 1988, 1992; L. Persson and L. Oksanen, unpublished analysis). Moreover, structural complexity covaries with primary productivity and influences interactions between planktivores and juvenile piscivores, providing an alternative explanation for the observed correlation between potential productivity and trophic dynamics (Persson and Eklöv 1995; Persson et al. 1999).

Trophic Interactions in Running Water

In spite of widespread omnivory, trophic cascades occur even in rivers, with three or four functional trophic guilds (Wootton and Power 1993; McIntosh and Townsend 1996; Huryn 1998). However, the energy constraint of EEH seems trivial; the dynamical food chain length is controlled by other factors (Power 1990, 1992; Wootton and Power 1993; Persson et al. 1996). In areas where streams are short and have little contact with each other, the impoverished predator fauna can be unable to break the defenses of herbivores. Consequently, two-link trophic dynamics are found even in productive streams. (Power 1984; T. Oksanen et al. 1995). In other cases, the well-defended herbivore is sensitive to physical disturbance, leading to disturbance-mediated variation in trophic dynamics (Power 1992). Three-link cascades appear to be typical for large, interconnected stream systems, but in the absence of large-mouthed predatory fishes, two-link trophic dynamics can emerge, even in major river systems (Power et al. 1985, 1988; M. E. Power, personal communication).

Littoral and Microbial Systems

In systems based on external inputs of organic material and filtering animals, exploitation of basal organisms does not require adaptations, which would prevent the consumer from being efficient predator of mobile animals, too. Hence, strong interactions can exist between basal organisms and top predators (Paine 1974). In these systems, the positive, indirect interaction between carnivores and basal organisms implied by HSS and EEH is unlikely to occur, and dynamics are likely to conform to the ideas of Menge and Sutherland (1976, 1987). In systems dominated by macroalgae, trophic cascades are found (Estes and Palmisano 1974; Estes and Duggins 1995). The same dichotomy emerges in microbial systems: the perspectives of HSS and EEH are corroborated in autotroph-based systems but not in systems based on external inputs of organic material (Kaunzinger and Morin 1998; Mikola and Setälä 1998; Naaem and Li 1998).

How to Proceed?

The main point emerging from the above review of trophic dynamics in autotroph-based ecosystems is the vulnerability of plants—including the mighty and seemingly invulnerable trees. All trees start as small seedlings, which mammals can consume without noticing. Thereafter, the survivors spend years as small saplings, which can be easily killed by girdling, and decades in the size category where they can be broken by motivated browsers. The widespread heathlands of western Europe and the denuded mountain slopes of Asia strikingly illustrate that trees need protection in order to regenerate. These enormous habitat changes are by far too widespread and encompass too inaccessible habitats to be explained as consequences of direct human impacts. Whether the protecting role of predators is primarily population dynamical (limitation of folivore densities) or evolutionary (giving elusiveness priority over ability to handle low-quality forage) is still difficult to judge. The two browsers that have played a pivotal role in the deforestation of Eurasia are the sheep (initially an alpine browser from the Middle East) and the goat (a domesticated ibex). Both originate from unproductive ecosystems. The famous natural experiment of Aldabra (Merton et al. 1976) has proceeded in evolutionary timescale. On the other hand, theoretical considerations based on optimal foraging (L. Oksanen 1990*b*, Hambäck 1998) and our still largely unpublished island data suggest that strict resource limitation in a seasonal environment, creating periodic starvation in winter, is strikingly damaging even for unpalatable woody plants. The situation can be clarified by additional long-term predator removal experiments,

performed in different environments and with focus on different taxa.

For future work, we wish to emphasize two methodological points. First, our hypotheses are judged by a jury of plants and animals, which does not care about persuasive arguments. If we manage to proceed in understanding the dynamics in living nature, we are on the winning side. If we manage to block this process, we are on the losing side and will end up in the company of Lysenko, no matter how persuasive we are in the short run. Second, as pointed out by Levins (1968), ecologists face a trade-off between generality and precision. At their best, general theories can organize our thinking and give directions for more specific ideas, but they will never suffice as comprehensive explanations of dynamics in any system. Our discussions on population cycles serves as an example. The basic ideas have been derived from EEH, but the explanation itself requires relaxation of the assumption that trophic guilds act as homogenous blocks and introduction of system-specific assumptions.

Our collective effort to try to understand the immense diversity of interactions in living nature amounts to an attempt to navigate through a narrow passage between the Scylla of dogmatism and the Charybdis of resignation. We must be critical, see nature as it is, and pursue the limitations of our favorite hypotheses. However, we also need general ideas, showing that everything is not a hopeless maze of special cases. There are even patterns, connected to simple and logical explanations, derived from first principles.

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